# "Big Match" with Lack of Information on One Side (Part II) 

By Sylvain Sorin, Strasbourg ${ }^{1}$

Abstract: This is the second paper on a class of stochastic games with incomplete information. As in Sorin [1984] we prove the existence of the asymptotic value ( $\lim v_{n}$ ) of the maxim and of the minmax although the infinite value may not exist. Nevertheless the results and the tools used are rather different from the previous case.

## 1 Introduction

As in the previous paper [Sorin, 1984] we consider a two-person zero-sum infinitely repeated game with incomplete information and absorbing states.

We are given two states of nature, hence two payoff matrices

$$
A=\left[\begin{array}{ll}
a_{11}^{*} & a_{12} \\
a_{21}^{*} & a_{22}
\end{array}\right] \text { and } B=\left[\begin{array}{ll}
b_{11}^{*} & b_{12} \\
b_{21}^{*} & b_{22}
\end{array}\right]
$$

with the left column absorbing (i.e. once any entry with a star ( ${ }^{*}$ ) is reached, all payoffs in the future will be equal to that entry. See Blackwell/Ferguson, and Kohlberg). Now one of these two matrices is chosen once and for all by the referee (with probability $p$ for $A$ ) and this choice is told to player $I$. The game is then played in stages. After each stage $n$ the players are told the previous moves $i_{n}, j_{n}$ by the referee, but the current payoff $q_{n}$ is not stated. The description of the game, including this sentence, is common knowledge. A player's (behavioral) strategy is the choice of a probability over his set of moves, at each stage, conditional on his information on the state and on the history (i.e. the sequence of moves) up to that stage.

We shall denote by $H_{m}$ the set of $m$-stage histories. Given the state such a history

[^0]determines a payoff at stage $m, q_{m}$, and an average payoff $\bar{q}_{m}$ which is the Cesaro mean of the payoffs up to stage $m$. Its expectation with respect to $p, \sigma$ and $\tau$ (strategies of the players) is denoted by $\bar{\gamma}_{m} \cdot \gamma_{m}$ is the expected payoff at stage $m$.
$\nu_{n}(p)$ is the value of the $n$ repeated game $G_{n}(p)$ with payoff $\bar{\gamma}_{n}$.
In order to study $G_{\infty}(p)$ we recall the following definitions [Mertens/Zamir].
$\underline{\nu}(p)$ is the maxmin of $G_{\infty}(p)$ if
i) $\forall \epsilon>0, \exists \sigma$ and $\exists N$ such that
$$
\bar{\gamma}_{n}(\sigma, \tau) \geqslant \underline{\nu}(p)-\epsilon \text { for all } \tau \text { and all } n \geqslant N
$$
ii) $\forall \epsilon>0, \forall \sigma, \exists \tau$ and $\exists N$ with
$$
\bar{\gamma}_{n}(\sigma, \tau) \leqslant \underline{v}(p)+\epsilon \text { as soon as } n \geqslant N .
$$

We shall refer to these conditions by saying that player $I(P I)$ can guarantee $\underline{v}$, (i), and that he cannot expect more, (ii).

The minmax $\bar{v}$ is defined in a dual way. $G_{\infty}(p)$ has a value $v_{\infty}$ iff $\bar{v}(p)=\underline{\nu}(p)$.
The "Big Match" of Blackwell and Ferguson is $G_{\infty}(0)$, and they proved the existence of $v_{\infty}$.

In Sorin [1984] the payoff matrices have the first row absorbing and the existence of $\lim v_{n}, \bar{v}$ and $\underline{\nu}$ is proved. Nevertheless there are games without a value. For the present class we obtain similar results, but the tools used are rather different. The main difficulty being for the minmax where PII faces a "stochastic game with vector payoffs" [Blackwell].

## 2 Maxmin

If $\Delta_{n}(p), n \in \mathbf{N} \cup\{+\infty\}$, is the repeated game where none of the players is informed, we recall [Kohlberg] that its value $u_{n}(p)$ exists and is constant w.r.t. $n$. This value will be denoted by $u$.
$H_{n}$ is the $\sigma$-field induced by $H_{n}$ on $H_{\infty}$ and $p_{n}$ is the posterior induced by $\sigma$, i.e. $p_{n}=\operatorname{Prob}_{\sigma}\left(A \mid H_{n-1}\right)$.

If $f$ is a real function on $[0,1], \operatorname{Cav} f$ is the smallest concave function greater than $f$ on $[0,1]$.

Finally we introduce some notations.
$L$ is the maximum absolute value of the payoff entries. If $\alpha$ is a probability distribution on the moves, $\tilde{\alpha}$ denotes the associated strategy identically independently distributed. If $x \in[0,1], \hat{x}$ denotes $1-x$.

## Proposition 1

$$
\underline{v}(p) \text { exists and } \underline{v}(p)=\operatorname{Cav} u(p) \text { on }[0,1] .
$$

## Proof

1) Let us first prove that $P I$ can guarantee $\operatorname{Cav} u(p)$. A general result for games with incomplete information states that if $P I$ can guarantee some payoff $f(p)$ in $G_{\infty}(p)$ he can also guarantee Cav $f(p)$ [see e.g. Sorin, 1979, 2.17]. Since $P I$ can guarantee $u(p)$ by playing non separating, i.e., by ignoring his information, the result follows.
2) It remains to show that $P I$ cannot expect more. The idea of the proof is now standard [see e.g. Mertens/Zamir, p. 205]: given PI's strategy, PII can compute the posteriors $p_{n}$ and, using the convergence of this martingale, can determine a stage $N$ after which $P I$ is essentially playing without using his information. From this stage on, PII can obtain $u\left(p_{N}\right)$ as a payoff, hence his expected average payoff will be at most $\operatorname{Cav} u(p)$.

So let $\sigma$ be a strategy for $P I$ and denote by $\widetilde{R}$ the strategy of $P I I$ defined by always playing Right. Given $\sigma$ and $\widetilde{R}$, the sequence $\left\{p_{n}\right\}$ is a martingale in $[0,1]$, hence its quadratic variation is bounded. It follows that, given $\epsilon>0$, we can define $N$ such that

$$
\begin{equation*}
E_{\sigma, \widetilde{R}} \sum_{n=1}^{\infty}\left(p_{n+1}-p_{n}\right)^{2} \leqslant E_{\sigma, \widetilde{R}} \sum_{n=1}^{N}\left(p_{n+1}-p_{n}\right)^{2}+\epsilon \tag{1}
\end{equation*}
$$

Let us define

$$
g_{n}(\sigma, \widetilde{R})=E\left(q_{n} \mid H_{n-1}\right) \text { and } \bar{\sigma}=E\left(\sigma \mid H_{n-1}\right) \text {. }
$$

Then we have [e.g. see Sorin [1979], 2.11]

$$
\begin{equation*}
\left|g_{n}(\sigma, \widetilde{R})-g_{n}(\bar{\sigma}, \widetilde{R})\right| \leqslant 2 L E_{\sigma, \tilde{R}}\left(\mid p_{n+1}-p_{n} \| H_{n-1}\right) . \tag{2}
\end{equation*}
$$

Moreover since $\bar{\sigma}$ is non separating, there exists a pure strategy $\tau^{*}$ of $P I I$ such that

$$
\begin{equation*}
g_{n}\left(\bar{\sigma}, \tau^{*}\right) \leqslant u\left(p_{n}\right) \tag{3}
\end{equation*}
$$

We can now describe the strategy $\tau$ for $P I I$ in $G_{\infty}$ :

- play according to $\widetilde{R}$ up to stage $N$;
- from stage $N+1$ on, play according to $\tau^{*}$.

In order to compute the payoff induced by $\sigma$ and $\tau$, we first define the stopping time $X$ by:

$$
N+X=\min \left[\left\{m ; j_{m}=\operatorname{Left}\right\} \cup\{+\infty\}\right] \text { and } X_{k}=X \wedge k
$$

Note that $X_{k}$ is $H_{N+k-1}$ - measurable.

It follows then from (2) and (3) that

$$
\begin{align*}
& (N+n) \bar{\gamma}_{N+n}(\sigma, \tau) \leqslant N L+E_{\sigma, \tau}\left[\sum_{m=1}^{X_{n}} u\left(p_{N+m}\right)+\left(n-X_{n}\right) u\left(p_{N+X_{n}}\right)\right]  \tag{4}\\
& +2 L E_{\sigma, T}\left[\sum_{m=1}^{X_{n}}\left[p_{N+m+1}-p_{N+m}\left|+\left(n-X_{n}\right)\right| p_{N+X_{n}+1}-p_{N+X_{n}}\right]\right.
\end{align*}
$$

But we have

$$
\begin{align*}
& E_{\sigma, r}\left[\sum_{m=1}^{X_{n}} u\left(p_{N+m}\right)+\left(n-X_{n}\right) u\left(p_{N+X_{n}}\right)\right] \leqslant E_{\sigma, \tau}\left[\sum_{m=1}^{X_{n}} \operatorname{Cav} u\left(p_{N+m}\right)\right. \\
& \left.+\left(n-X_{n}\right) \operatorname{Cav} u\left(p_{N+X_{n}}\right)\right] \\
& \leqslant n E_{\sigma, \tau} \operatorname{Cav} u\left[\frac{1}{n}\left(\sum_{m=1}^{X_{n}} p_{N+m}+\left(n-X_{n}\right) p_{N+X_{n}}\right)\right] \\
& \leqslant n \operatorname{Cav} u\left[\frac{1}{n} E_{\sigma, r}\left(\sum_{m=1}^{X_{n}} p_{N+m}+\left(n-X_{n}\right) p_{N+X_{n}}\right)\right] \tag{5}
\end{align*}
$$

(by Jensen's inequality).

$$
\text { Define, for } 1 \leqslant k \leqslant n, Y_{k}=\sum_{m=1}^{X_{k}} p_{N+m}+\left(n-X_{k}\right) p_{N+X_{k}}
$$

Write

$$
E_{\sigma, \tau} Y_{n}=E_{\sigma, \tau}\left(1_{X_{n}<n} Y_{n}\right)+E_{0, \tau}\left(1_{X_{n}=n} Y_{n}\right)
$$

But on $X_{n}<n, X_{n}=X_{n-1}$, hence $Y_{n}=Y_{n-1}$, so that

$$
\begin{equation*}
E_{\sigma, \tau}\left(1_{X_{n}<n} Y_{n}\right)=E_{\alpha_{y} t}\left(1_{X_{n}<n} Y_{n-1}\right) \tag{6}
\end{equation*}
$$

Furthermore on $X_{n}=n$, we have $X_{n-1}=n-1$, hence (with $E_{\sigma, \tau}=E$ )

$$
\begin{align*}
E\left(1_{X_{n}=n} Y_{n}\right) & =E\left(E 1_{X_{n}=n} Y_{n} \mid H_{N+n-1}\right) \\
& =E\left[1_{X_{n}=n}\left(\sum_{m=1}^{n-1} p_{N+m}+E\left(p_{n+N} \mid H_{N+n-1}\right)\right)\right] \\
& =E\left[1_{X_{n}=n}\left(\sum_{m=1}^{n-1} p_{N+m}+p_{N+n-1}\right)\right] \\
& =E\left[1_{X_{n}=n}\left(\sum_{m=1}^{X_{n-1}} p_{N+m}+p_{N+X_{n-1}}\right)\right] \\
& =E\left(1_{X_{n}=n} Y_{n-1}\right)
\end{align*}
$$

It follows from (6) and (7) that

$$
\begin{equation*}
E\left(Y_{n}\right)=E\left(Y_{n-1}\right)=E\left(Y_{1}\right)=E\left(n p_{N+1}\right)=n p \tag{8}
\end{equation*}
$$

As for the last term in the right member of (4) we obtain

$$
\begin{aligned}
M & =E_{\sigma, \tau}\left(\sum_{m=1}^{X_{n}}\left|p_{N+m+1}-p_{N+m}\right|+\left(n-X_{n}\right)\left|p_{n+X_{n}+1}-p_{N+X_{n}}\right|\right) \\
& =E_{\sigma, \tau}\left(\sum_{m=1}^{n}\left|p_{N+m+1}-p_{N+m}\right| Z_{m}\right) \\
\text { with } Z_{m} & = \begin{cases}0 & \text { if } m>X_{n} \\
n+1-X_{n} & \text { if } m=X_{n} \\
1 & \text { if } m<X_{n} .\end{cases}
\end{aligned}
$$

We obviously have $\sum_{m=1}^{n} Z_{m}=n$.
Now, note that the laws of the $Z_{m}$ are the same under $\tau$ and $\widetilde{R}$ since $\tau$ and $\widetilde{R}$ coincide up to stage $X-1$, and moreover the posteriors $p_{N+m}$ and $p_{N+m+1}$ are the same under $\tau$ and $\tilde{R}$ on $Z_{m} \neq 0$. It follows that

$$
M=E_{\sigma, \tilde{R}}\left(\sum_{m=1}^{n}\left|p_{N+m+1}-p_{N+m}\right| Z_{m}\right) .
$$

Using the Cauchy-Schwartz inequality and (1) we now obtain

$$
\begin{align*}
M & \leqslant E_{\sigma, \tilde{R}}\left[\left(\sum_{m=1}^{n}\left(p_{N+m+1}-p_{N+m}\right)^{2}\left(\sum_{m=1}^{n} Z_{m}^{2}\right)\right)^{1 / 2}\right] \\
& \leqslant\left[E_{\sigma, \tilde{R}} \sum_{m=1}^{n}\left(p_{N+m+1}-p_{N+m}\right)^{2} E_{\sigma, \tilde{R}} \sum_{m=1}^{n} Z_{m}^{2}\right]^{1 / 2} \\
& \leqslant \sqrt{\epsilon} \cdot n . \tag{9}
\end{align*}
$$

From (4), (5), (8) and (9) we finally get

$$
(n+N) \bar{\gamma}_{n+N}(\sigma, \tau) \leqslant N L+n \operatorname{Cav} u(p)+2 \operatorname{Ln} \sqrt{\epsilon}
$$

Thus $n \geqslant \frac{N}{\sqrt{\epsilon}}$ implies

$$
\bar{\gamma}_{n+N}(\sigma, \tau) \leqslant \operatorname{Cav} u(p)+4 L \sqrt{\epsilon}
$$

## Remark 1

It is easy to see that the above proof remains true for any finite sets $K, I, J$, as long as all of the matrices $A^{k}, k \in K$, are of the following type: the first column is absorbing and there is no other absorbing payoffs. The only modification is in the definition of $\widetilde{R}$. Let $T=\left\{\tau \mid \forall m, \forall h_{m-1}, \tau\left(h_{m-1}\right)\right.$ is supported by $\left.J-\{1\}\right\}$. Then choose $\tilde{\tau}$ and $N$ such that

$$
\sup _{\tau \in T} E_{\sigma, \tau} \sum_{n=1}^{\infty}\left(p_{n+1}-p_{n}\right)^{2} \leqslant E_{\sigma, \tilde{T}} \sum_{n=1}^{N}\left(p_{n+1}-p_{n}\right)^{2}+\epsilon
$$

## $3 \operatorname{Lim} v_{n}$

## Proposition 2

$\lim _{n \rightarrow \infty} v_{n}(p)$ exists and equals $\operatorname{Cav} u(p)$ on $[0,1]$.

## Proof

1) We know that $v_{n}(p) \geqslant u_{n}(p)=u(p)$ and that $v_{n}$ is concave, hence we have $v_{n}(p) \geqslant \operatorname{Cav} u(p)$ for all $n$.
2) Let $\sigma$ be a strategy for $P I$.

$$
\text { Since } \left.E_{\sigma, \tilde{R}}\left(\sum_{m=1}^{n}\left(p_{m+1}-p_{m}\right)^{2}\right) \text { is bounded by some } M \text { (uniformly in } \sigma \text { and } n\right)
$$

there are at most $n^{3 / 4}$ stages $m$ with

$$
\begin{equation*}
E_{\sigma, \tilde{R}}\left(p_{m+1}-p_{m}\right)^{2} \geqslant \frac{M}{n^{3 / 4}} \tag{10}
\end{equation*}
$$

We denote by $R(n)$ the set of such stages, and define $S(n)=\{1, \ldots, n\} \backslash R(n)$. Given $m \in S(n)$, it follows that the probability of the set $H_{m-1}^{\prime}$ of histories $h_{m-1}$ such that

$$
\begin{equation*}
E_{\sigma, \tilde{R}}\left(\left(p_{m+1}-p_{m}\right)^{2} \mid h_{m-1}\right)>\frac{M}{n^{1 / 2}} \tag{11}
\end{equation*}
$$

is less than $n^{-1 / 4}$.
We can now describe the strategy $\tau$ of $P I I$ :

- play $\widetilde{R}$ if $m \in R(n)$, or if $h_{m-1} \in H_{m-1}^{\prime}$ with $m \in S(n)$;
- play according to $\tau^{*}$ otherwise, where as in the previous proof $\tau^{*}$ is a pure strategy satisfying (3).
We introduce the following stopping time

$$
X=\min \left(\left\{m ; j_{m}=L, 1 \leqslant m \leqslant n\right\} \cup\{n\}\right) .
$$

It follows then, using (2), (10) and (11) that

$$
\begin{align*}
& n \bar{\gamma}_{n}(\sigma, \tau) \leqslant 2 n^{3 / 4} L+2 n \cdot n^{-1 / 4} L \\
& +E_{\sigma, \tau}\left[\sum_{m=1}^{X} u\left(p_{m}\right)+(n-X) u\left(p_{X}\right)\right]  \tag{12}\\
& +2 L E_{\sigma, \tau}\left[\sum_{m=1}^{X}\left|p_{m+1}-p_{m}\right|+(n-X)\left|p_{X+1}-p_{X}\right|\right]
\end{align*}
$$

First, as in the previous proof, it is easy to see that

$$
E_{\sigma, \tau}\left(\sum_{m=1}^{X} u\left(p_{m}\right)+(n-X) u\left(p_{X}\right)\right) \leqslant \operatorname{Cav} u(p)
$$

As for the last term in the right member of (12) we can take the expectation with respect to $\sigma, \widetilde{R}$ since $\tau$ and $\widetilde{R}$ coincide up to stage $X-1$, and then majorize by

$$
E_{\sigma, \tilde{R}}\left(\sum_{m=1}^{n}\left|p_{m+1}-p_{m}\right|\right)+n E_{\sigma, \tilde{R}}\left(\left|p_{X+1}-p_{X}\right| 1_{X<n}\right)
$$

But we have

$$
E_{\sigma, \tilde{R}}\left(\sum_{m=1}^{n}\left|p_{m+1}-p_{m}\right|\right) \leqslant \sqrt{M n}
$$

by Cauchy Schwartz inequality and

$$
\begin{aligned}
E_{\sigma, \tilde{R}}\left(\left|p_{X+1}-p_{X}\right| \mid H_{X-1}\right) & \left.\leqslant E_{\sigma, \tilde{R}}\left(p_{X+1}-p_{X}\right)^{2} \mid H_{X-1}\right)^{1 / 2} \\
& \leqslant \frac{\sqrt{M}}{n^{1 / 4}} \text { if } X<n, \text { by }(11)
\end{aligned}
$$

Coming back to (12) we obtain

$$
n \bar{\gamma}_{n}(\sigma, \tau) \leqslant 2 L n^{3 / 4}+2 L n^{3 / 4}+n \operatorname{Cav} u(p)+2 L \sqrt{M} n^{1 / 2}+2 L \sqrt{M} n^{3 / 4}
$$

hence there exists some $K \in \mathbf{R}^{+}$such that

$$
\bar{\gamma}_{n}(\sigma, \tau) \leqslant \operatorname{Cav} u(p)+\frac{\mathrm{K}}{n^{1 / 4}} \text { for all } n .
$$

## Remark 2

The previous proof still holds for the games described in Remark 1. But now $\widetilde{R}$ has to be replaced by a "stage by stage" best reply in $T$ to $\bar{\sigma}$.

## Remark 3

If $v_{\lambda}(p)$ is the value of the game $G_{\lambda}(p)$ with payoff $\sum_{m=1}^{\infty} \lambda(1-\lambda)^{m-1} \gamma_{m}$, it is easy to see that $\lim _{\lambda \rightarrow 0} v_{\lambda}(p)=\operatorname{Cav} u(p)$. The first part of the proof is exactly like that in Proposition 2. The second half uses the same kind of strategy, defining first $N=\lambda^{-3 / 4}$ and a set of exceptional stages where $E\left(p_{m+1}-p_{m}\right)^{2} \geqslant \frac{M}{N}$. Now for each "regular" stage $m$ the probability of exceptional histories, i.e. such that $\mathrm{E}\left(\left(p_{m+1}-p_{m}\right)^{2} \mid h_{m-1}\right) \geqslant \frac{M}{N^{2 / 3}}$ is less than $N^{1 / 3}$. We thus obtain a majorization of the payoff by some $\operatorname{Cav} u(p)+0(1) \cdot\left(1-(1-\lambda)^{N+1}+N^{-1 / 3}+\left(1 / N^{2 / 3}\right)^{1 / 2}\right.$ $\left.+\lambda^{1 / 2}\right)$, hence $\operatorname{Cav} u(p)+0\left(\lambda^{1 / 4}\right)$.

## 4 Minmax

In this section we shall prove the following

## Theorem 3

$\bar{v}(p)$ exists.
In order to get this result we shall first assume

$$
v(A)=v(B)=0
$$

by subtracting $p v(A)+\hat{p} v(B)$ from all the payoffs.
We shall split the games into several cases for each of which optimal minmax strategies for $P I I$ and best responses for $P I$ will be constructed and an explicit formula for $\bar{v}(p)$ will be given.

## First case

$$
\left(a_{11}-a_{21}\right)\left(b_{11}-b_{21}\right) \geqslant 0 .
$$

By changing the name of the lines if necessary, we can assume

$$
\begin{equation*}
a_{21} \geqslant a_{11} \text { and } b_{21} \geqslant b_{11} \tag{13}
\end{equation*}
$$

Let us introduce the following notations and definitions.

$$
\begin{align*}
& x^{+}=\max (x, 0) \text { for } x \in \mathbf{R} . \\
& c_{j}(t)=c_{1_{j}} t+c_{2_{j}} \hat{t}, j=1,2, c=a, b \text { for } t \in[0,1] . \\
& Q=\{\rho ; \rho \text { positive Borel measure on }[0,1] \text { with total mass } \leqslant 1\} . \\
& \begin{aligned}
\rho(x)=\rho([0, x]) . \\
\begin{aligned}
& w(p)=\inf _{\rho \in Q} \sup _{\substack{x \in[0,1] \\
y \in[0,1]}}\left[p \int_{0}^{x} a_{1}(t) d \rho(t)+(1-\rho(x)) a_{2}(x)^{+}\right. \\
&\left.+\hat{p} \int_{0}^{y} b_{1}(t) d \rho(t)+(1-\rho(y)) b_{2}(y)^{+}\right] .
\end{aligned}
\end{aligned} .
\end{align*}
$$

Then we have

## Proposition 4

If (13) holds, $\bar{v}(p)$ exists and equals $w(p)$.
The proof of this proposition will follow from the two next lemmas.

## Lemma 5

PII cannot expect less than $w(p)$.

## Proof

The idea of the proof is the same as in Sorin [1984], Lemma 21. Knowing $\tau, P I$ starts by playing Bottom until he reaches the maximum of the probability of getting an absorbing payoff at this level. From this time on he increases his frequency slowly (i.e. he will use $(\epsilon, 1-\epsilon)$ ) until the maximum of the "absorbing" probability is reached and so on up to some level $x$. Then he will get $c_{2}(x)$ if he stays at $\tilde{x}$ or 0 by playing optimally. This strategy obviously induces a probability $d \rho(t)$ of getting an absorbing payoff $c_{1}(t)$, and it follows by (14) that the payoff will be at least $w(p)$.

First let $m$ be the stopping time $\min \left\{m ; j_{m}=L\right\} \cup\{+\infty\}$ and choose a large $N$ in $\mathbf{N}$.

Given $\epsilon>0$ and $\tau$ a strategy for PII, define

$$
\begin{aligned}
& \sigma_{0}=\tilde{\text { Bottom }} \\
& P^{*}(0)=\operatorname{Prob}_{\sigma_{0}, \tau}(\underset{\sim}{m}<+\infty)
\end{aligned}
$$

then $n_{0}$ and $P(0)$ such that

$$
P(0)=\operatorname{Prob}_{\sigma_{0}, \tau}\left(\underset{\sim}{m} \leqslant n_{0}\right)>P^{*}(0)-\epsilon .
$$

Given $\sigma_{r-1}, n_{r-1}$, define inductively

$\sigma_{r}$ : play according to $\sigma_{r-1}$ up to stage $n_{r-1}$, then $\left(\frac{r}{N},\left(\frac{r}{N}\right)\right)$

$$
P^{*}(r)=\operatorname{Prob}_{\sigma_{r}, \tau}(\underset{\sim}{(m}<+\infty)
$$

then $n_{r} \geqslant n_{r-1}$ and $P(r)$ with

$$
P(r)=\operatorname{Prob}_{\sigma_{r}, \tau}\left(\underset{\sim}{m} \leqslant n_{r}\right)>P^{*}(r)-\epsilon .
$$

Now if $P I$ uses $\sigma_{r}$ up to stage $n_{r}$ in game $A$, and then plays $\left(\frac{r}{N},\left(\frac{\hat{r}}{N}\right)\right)$ if $a_{2}(r / N) \geqslant 0$, or optimally in game $A$ otherwise, the expected payoff in game $A$ for $n \geqslant n_{r}$ will satisfy

$$
\bar{\gamma}_{n}^{A}\left(\sigma_{r}, \tau\right) \geqslant P(0)\left[a_{1}(0)-2 L \frac{n_{0}}{n}\right]
$$

$$
\begin{aligned}
& +(P(1)-P(0))\left[a_{1}\left(\frac{1}{N}\right)-2 L \frac{n_{1}}{n}\right] \\
& +\ldots \\
& +(P(r)-P(r-1))\left[a_{1}\left(\frac{r}{N}\right)-2 L \frac{n_{r}}{n}\right] \\
& +(1-P(r))\left[a_{2}\left(\frac{r}{N}\right)^{+}-2 L \frac{n_{r}}{n}\right] \\
& -2\left(P^{*}(r)-P(r)\right) L .
\end{aligned}
$$

If $\mu \in Q$ is the atomic measure with mass $P(\ell)-P(\ell-1)$ at point $\ell / N$, then for $n$ large enough we obtain

$$
\bar{\gamma}_{n}^{A}\left(\sigma_{r}, \tau\right) \geqslant \int_{0}^{r / N} a_{1 .}(t) d \mu(t)+\left(1-\mu\left(\frac{r}{N}\right) a_{2}\left(\frac{r}{N}\right)^{+}-4 \epsilon L .\right.
$$

Now there exists $r^{*} \in \mathbf{N}, 0 \leqslant r^{*} \leqslant N$ which realizes the supremum over all reals $r \in[0, N]$ of the right member within $\frac{2 L}{N}$.

A similar construction for game $B$ induces a strategy $\sigma$ for $P I$ such that for $n$ large enough

$$
\begin{aligned}
\bar{\gamma}_{n}(\sigma, \tau) \geqslant & p \sup _{0 \leqslant x \leqslant 1} \int_{0}^{x} a_{1}(t) d \mu(t)+(1-\mu(x)) a_{2}(x)^{+} \\
& +\hat{p} \sup _{0 \leqslant y \leqslant 1} \int_{0}^{y} b_{1}(t) d \mu(t)+(1-\mu(y)) b_{2}(y)^{+} \\
& -4 \in L-\frac{2 L}{N}
\end{aligned}
$$

hence the result is obtained by choosing $N$ large enough.
Q.E.D.

In order to prove that PII can guarantee $w(p)$ we shall use "Big Match" strategies, hence we need the following definitions and results. Let $\Gamma_{s}^{+}$be the zero sum two person infinitely repeated game with payoff matrix

$$
\left[\begin{array}{cc}
-(1-s)^{*} & (1-s) \\
s^{*} & -s
\end{array}\right]
$$

(The "Big Match" of Blackwell/Fergusson is precisely $\Gamma_{1 / 2}^{+}$.) As above we define the stopping time $\underset{\sim}{m}$ and the payoff $q_{n}^{s}$ at stage.

We also introduce $\tilde{t}_{n}=\frac{1}{n} \#\left\{m ; i_{m}=T, 1 \leqslant m \leqslant n\right\}$ which is the frequency of Top up to stage $n$.

Then we have:

## Proposition 6

[Blackwell/Fergusson, Kohlberg].
$\forall \epsilon>0, \forall \delta>0, \exists N_{s}$ and $\tau_{s}$ strategy of PII in $\Gamma_{s}^{+}$such that for any $\sigma$

$$
\begin{align*}
& \left.\operatorname{Prob}_{\sigma, \tau_{s}} \underset{\sim}{(m} \leqslant n\right) E_{\sigma, \tau_{s}}\left(q_{m}^{s} \mid \underset{\sim}{m} \leqslant n\right) \leqslant \epsilon \quad \forall n  \tag{15}\\
& \operatorname{Prob}_{\sigma, \tau_{s}}\left(\underset{\sim}{m}<n \mid \tilde{t}_{n} \geqslant s+\delta\right) \geqslant 1-\epsilon \quad \forall n>N_{s} \tag{16}
\end{align*}
$$

Using this result we shall prove

## Lemma 7

PII can guarantee $w(p)$.

## Proof

The idea of the proof there is also similar to Sorin [1984], Propositon 26.
Let $\rho$ be $\epsilon$-optimal in (14). Then PII uses $\tau_{s}$ with probability $d \rho(s)$. It follows from (13) that a best response of $P I$ is to increase his frequency, starting from 0 , in order to achieve the greatest absorbing payoff, and then to decrease it if necessary, which gives (14).

Let us start with $\bar{\rho}, \theta / 2$ optimal in (14) and choose $\rho$ to be a discrete " $\theta / 2$ approximation" of $\bar{\rho}$ as in Sorin [1984], Lemma 28, i.e. such that

$$
\begin{align*}
p\left[\int_{0}^{x} a_{1}(t) d \rho(t)\right. & \left.+(1-\rho(x)) a_{2}(x)^{+}\right]+  \tag{17}\\
& +\hat{p}\left[\int_{0}^{y} b_{1}(t) d \rho(t)+(1-\rho(y)) b_{2}(y)^{+}\right] \leqslant w(p)+\theta
\end{align*}
$$

for all $x, y$ in $[0,1]$.
Let $\left\{s_{r}: r=0, \ldots, R\right\}$ be the finite support of $\rho$. We can assume by selecting a refinement if necessary that $s_{0}=0, s_{R}=1$, and $s_{r}-s_{r-1}<\eta$, where $R$ is bounded by some $R(\theta, \eta)$ uniformly in $\bar{\rho}$.

We shall use the following notations.

$$
\tau_{s_{r}}=\tau_{r}, \rho\left(\left\{s_{r}\right\}\right)=d \rho_{r}, \sum_{0}^{r} \rho\left(\left\{s_{r}\right\}\right)=\rho_{r}, N_{s_{r}}=N_{r}
$$

Also let $N=\max N_{r}$.
The strategy for PII is as follows: First choose $r^{*} \in R$ according to the distribution defined by $\operatorname{Prob}\left(r^{*}=r\right)=d \rho_{r}, r=0, \ldots, R-1$ and $\operatorname{Prob}\left(r^{*}=R\right)=1-$ $-\rho_{R-1}$. If $r^{*}=0$, play Left at the first stage and define $Y_{0}=1$. If $0<r^{*}<R$ play Right until stage $Y_{r^{*}}-1$, and Left at stage $Y_{r^{*}}$, where the stopping times $Y_{r}$ are defined inductively by

$$
\begin{aligned}
& Y_{1}=\min \left\{m: j_{m}=L\right\} \text { is induced by } \sigma \text { and } \tau_{1} ; \\
& Y_{2}=\min \left\{m: j_{m}=L\right\} \text { is induced by } \sigma \text { and } \tau_{1} \text { up to stage } Y_{1}-1 \\
& \quad \text { and then } \tau_{2} ;
\end{aligned}
$$

$Y_{r}$ is induced by $\sigma \tau_{1}$ up to stage $Y_{1}-1, \ldots, \tau_{r-1}$ up to stage $Y_{r-1}-1$ and then $\tau_{r}$.

Finally if $r^{*}=R$, always play Right (i.e. $Y_{R} \equiv+\infty$ ).
We shall prove that $\forall \epsilon_{0}>0$ the average payoff in game $A$ for $n$ large enough will be majorized uniformly for any strategy $\sigma^{A}$ by $\alpha+\epsilon_{0}$ where

$$
\begin{equation*}
\alpha=\sup _{0 \leqslant x \leqslant 1} \alpha(x) \text { and } \alpha(x)=\int_{0}^{x} a_{1}(t) d \rho(t)+(1-\rho(x)) a_{2}(x)^{+} . \tag{18}
\end{equation*}
$$

Given $n, \sigma_{A}$ and $\tau$ we define

$$
Z_{r}=\min \left(Y_{r}, n+1\right), r=0, \ldots, R
$$

and

$$
\begin{aligned}
& X_{0}=0, X_{r}=Z_{r}-Z_{r-1}, \text { hence } \sum_{r} X_{r}=n \\
& t_{r}=1_{\left\{i_{Z_{r}}=T\right\}}, \bar{t}_{r}=\frac{1}{X_{r}} \#\left\{i_{m}=T ; Z_{r-1} \leqslant m<Z_{r}\right\} .
\end{aligned}
$$

Now since the strategy of $P I I$ is independent of $r^{*}$, up to stage $Y_{r^{*}}$ we obtain

$$
\begin{align*}
n \bar{\gamma}_{n}^{A}(\sigma, \tau)=E\left(\sum _ { 1 } ^ { R } X _ { r } \left[d \rho_{0} a_{1}\left(t_{0}\right)+\ldots\right.\right. & +d \rho_{r-1} a_{1}\left(t_{r-1}\right)+  \tag{19}\\
& \left.+\left(1-\rho_{r-1} a_{2}\left(\overline{t_{r}}\right)\right]\right)
\end{align*}
$$

Let us first consider the term with $a_{2}(\cdot)$.
i) If $a_{22}>a_{12}$ with $a_{22}>0$, then $v(A)=0$ implies $a_{21} \leqslant 0$, hence $n \bar{\gamma}_{n}^{A}(\sigma, \tau)$ $\leqslant \alpha(0)=a_{21} d \rho_{0}+\left(1-\rho_{0}\right) a_{22}$ by (13), and the result follows.
ii) If $a_{22}>a_{12}$ with $a_{22}=0$, then $a_{2}\left(\overline{t_{r}}\right) \leqslant 0=a_{2}\left(s_{r-1}\right)^{+} \forall r$
iii) If $a_{22} \leqslant a_{12}$ we majorize the coefficient of $a_{12}-a_{22}$ :

$$
E\left(X_{r} \bar{t}_{r}\right)=E\left(1_{X_{r}<N} X_{r} \bar{t}_{r}\right)+E\left(1_{X_{r} \geqslant N} X_{r} \bar{t}_{r}\right) .
$$

For the second term, since during these $X_{r}$ stages from $Z_{r-1}$ up to $Z_{r}-1, P I I$ is using $\sigma_{r}$, it follows from (16) that

$$
E\left(X_{r} \bar{t}_{r}\right) \leqslant N+E\left(X_{r}\right)\left(s_{r}+\delta+\epsilon\right) \leqslant N+E\left(X_{r}\right)\left(s_{r-1}+\delta+\eta\right)+\epsilon n
$$

Coming back to (19) and using (13) we obtain in cases ii) and iii)

$$
\begin{equation*}
n \bar{\gamma}_{n}^{A}(\sigma, \tau) \leqslant E\left(\sum_{1}^{R} X_{r} \alpha\left(s_{r-1}\right)\right)+R N L+n L(\delta+\eta)+R L \epsilon n+L \Delta \tag{20}
\end{equation*}
$$

with

$$
\Delta=E\left[\sum_{1}^{R} X_{r}\left(d \rho_{0}\left(s_{0}-t_{0}\right)+\ldots+d \rho_{r-1}\left(s_{r-1}-t_{r-1}\right)\right)\right]
$$

Hence

$$
\Delta \leqslant \sum_{i=1}^{R} d \rho_{r-1} E\left[\sum_{\ell=r}^{R} X_{\ell}\left(s_{r-1}-t_{r-1}\right)\right]
$$

Note that $s_{r-1}-t_{r-1}=-\left(1-s_{r-1}\right) t_{r-1}+s_{r-1}\left(1-t_{r-1}\right)$ is the absorbing payoff in $\Gamma_{s_{r-1}}$ and $\sum_{\ell=r}^{R} X_{\ell}=\left(n+1-Y_{r}\right)^{+}$is the number of stages during which $\sigma_{r-1}$ induces such an absorbing payoff. It follows then from (15) that

$$
E\left(\sum_{\ell=r}^{R} X_{\ell}\left(s_{r-1}-t_{r-1}\right)\right) \leqslant \epsilon n .
$$

Substituting in (20) we obtain

$$
n \bar{\gamma}_{n}^{A}(\sigma, \tau) \leqslant n \alpha+R N L+n L(\delta+\eta)+R L \epsilon n+L \in n .
$$

Obviously, a same result holds for $\bar{\gamma}_{n}^{B}$.

Given $\epsilon_{0}$, we take $\theta=\frac{\epsilon_{0}}{2}$. Then $\eta=\frac{\epsilon_{0}}{8 L}$, which determines some $R(\theta, \eta)$. We define $\tau_{s}$ according to $\delta=\frac{\epsilon}{8 L}$ and $\epsilon=\frac{\epsilon_{0}}{8 L(R+1)}$. This defines $N_{s}$, hence $N$. It follows then that $n \geqslant \frac{8 R N L}{\epsilon_{0}}$ implies $\bar{\gamma}_{n}(\sigma, \tau) \leqslant w(p)+\epsilon_{0}$.

This completes the proof in the first case.
For the other cases it is more convenient to work in the space of vector payoffs induced by $A$ and $B$, and to determine the sets that PII can approach [see Blackwell, 1956]. Some definitions follow.

PII can approach $(x, y) \in \mathbf{R}^{2}$ if, $\forall ' \epsilon>0, \exists \tau$ and $\exists N$ such that, $\forall \sigma, \forall n \geqslant N$,

$$
\begin{aligned}
& \bar{\gamma}_{n}^{A}(\sigma, \tau) \leqslant x+\epsilon \\
& \bar{\gamma}_{n}^{B}(\sigma, \tau) \leqslant y+\epsilon
\end{aligned}
$$

where $\bar{\gamma}_{n}^{A}$ is the average expected payoff in game $A$.
$D_{I I}$ is the set of vector payoffs that PII can approach, and note that $D_{I I}$ is closed, convex, and $D_{I I}=D_{I I}+\left(\mathbf{R}^{+}\right)^{2}$.

Given an half space $D(p, \alpha)=\left\{x, y ; p x+p^{\prime} y \geqslant \alpha\right\}, p \in[0,1], \alpha \in \mathbf{R}$, we say that PI can force $D(p, \alpha)$ if $\forall \tau, \forall \epsilon, \exists \sigma$ and $\exists N$ such that for all $n \geqslant N p \gamma_{n}^{A}(\sigma, \tau)+\hat{p} \gamma_{n}^{B}(\sigma, \tau) \geqslant \alpha-\epsilon$.

Note that if $P I$ can force $D(p, f(p))$, he can also force $D(p, \operatorname{Cav} f(p))$.
In fact, let $p_{1}$ and $p_{2}$ be such that Cav $f(p) \leqslant \lambda f\left(p_{1}\right)+(1-\lambda) f\left(p_{2}\right)+\frac{\epsilon}{2}$ and $\lambda p_{1}+(1-\lambda) p_{2}=1$.

Given $\tau$ and $\frac{\epsilon}{2}$ note $\sigma_{1}$ for $\sigma\left(p_{1}, f\left(p_{1}\right), \tau, \frac{\epsilon}{2}\right)$ as defined above and likewise for $\sigma_{2}$.
Let $\sigma^{A}$ be $\sigma_{1}^{A}$ with probability $\frac{\lambda \hat{p}_{1}}{p}, \sigma_{2}^{A}$ otherwise, and let $\sigma^{B}$ be $\sigma_{1}^{B}$ with probability $\frac{\lambda p_{1}}{\hat{p}}, \sigma_{2}^{B}$ otherwise. Then $\sigma$ forces $D(p, \operatorname{Cav} f(p))$.

Denote by $D_{I}$ the intersection of the sets $D(p, \alpha)$ that $P I$ can force. The existence of $\bar{\nu}$ is now equivalent to the fact that $D_{I}=D_{I I}$, denoted by $D$, and then

$$
\bar{v}(p)=\min _{(x, y) \in D}\{p x+(1-p) y\}
$$

Redefining the games if necessary we can assume
(I) $\quad a_{11}>a_{21}$ and $b_{11}<b_{21}$
(and since $v(A)=v(B)=0$ we have $a_{11} \geqslant 0$ and $b_{21} \geqslant 0$ ).
We introduce some notation

$$
\begin{aligned}
& T^{*}=\left(a_{11}, b_{11}\right), B^{*}=\left(a_{21}, b_{21}\right) \\
& X=\left(a_{22}^{+}, 0\right), Y=\left(0, b_{12}^{+}\right), Z=\left(a_{22}^{+}, b_{12}^{+}\right) .
\end{aligned}
$$

If $P_{1}$ and $P_{2}$ are two points in $\mathbf{R}^{2}$ on a line $p x+(1-p) y=\alpha, p \in[0,1]$, then $H\left(P_{1}, P_{2}\right)$ is $D(p, \alpha)$.

Finally, $H_{x}=\{(x, y): x \geqslant 0\}$ and similarly for $H_{y}$.

## Second case

We now assume
(II) $\max \left(a_{12}, a_{22}, 0\right)=a_{22}^{+}, \max \left(b_{12}, b_{22}, 0\right)=b_{12}^{+}$
(III) $Z \in H\left(T^{*}, B^{*}\right)$.

## Lemma 8

PI can force $H\left(T^{*}, Y\right), H\left(B^{*}, X\right)$ and $H\left(B^{*}, T^{*}\right)$.

## Proof

1) We show first that $P I$ can force $H\left(T^{*}, Y\right)$ (hence $H\left(B^{*}, X\right)$ by symmetry). Given $\tau$, let $\tilde{T}=\tilde{T o p}$ and define

$$
\theta=\operatorname{Prob} \underset{T, \tau}{\sim}(\underset{\sim}{( }<+\infty) .
$$

By playing always $\tilde{T}$, or by switching after a large number of stages to an optimal strategy in the corresponding game, $P I$ will reach

$$
\begin{aligned}
& \theta a_{11}+(1-\theta) \max \left(a_{12}, v(A)\right) \text { in game } A \\
& \theta b_{11}+(1-\theta) \max \left(b_{12}, v(B)\right) \text { in game } B .
\end{aligned}
$$

and this vector payoff dominates weakly $\theta T^{*}+(1-\theta) Y$.
2) Now let us introduce $\sigma_{0}$ and $N_{0}$ such that

$$
\operatorname{Prob}_{\sigma_{0}, \tau}\left(\underset{\sim}{m} \leqslant N_{0}\right) \geqslant \sup _{\sigma} \operatorname{Prob}_{\sigma, \tau}(\underset{\sim}{m}<+\infty)-\epsilon .
$$

Then $P I$ uses $\sigma_{0}$ up to stage $N_{0}$, and then plays Bottom or optimally in game $A$ (and symmetrically for $B$ ). It follows that for large enough $n$ that the vector payoff will be at least some

$$
\theta W^{*}+(1-\theta) Z+3 \epsilon L
$$

where $W^{*}$ is an absorbing payoff on the segment $\left[B^{*}, T^{*}\right]$. Now (III) implies the result.
Q.E.D.

We are now in position to state

## Proposition 9

If (I), (II), (III) hold, then

$$
D_{I}=D_{I I}=D=H_{x} \cap H_{y} \cap H\left(B^{*}, T^{*}\right) \cap H\left(T^{*}, Y\right) \cap H\left(B^{*}, X\right) .
$$

## Proof

Since $v(A)=v(B)=0$, we obviously have $D_{I} \subset H_{x} \cap H_{y}$, hence $D_{I} \subset D$ by

## Lemma 9.

Hence it remains to prove $D \subset D_{I I}$, and for this it is sufficient to show that the extreme points of the (strict) Pareto boundary $\bar{D}$ of $D$ belongs to $D_{I I}$.

Let us denote by $\bar{X}=(\bar{x}, 0)$ and $\bar{Y}=(0, \bar{y})$ the points on the axes of $\bar{D}$, and let us first prove that $P I I$ can approach $\bar{X}$ and $\bar{Y}$.

Let $\tau_{B}$ an $\eta_{B}$-optimal strategy for $P I I$ in the infinitely repeated game with payoff matrix $B$ satisfying

$$
\begin{align*}
& n \geqslant N_{B} \Rightarrow \bar{\gamma}_{n}^{B}\left(\sigma, \tau_{B}\right) \leqslant \eta_{B}  \tag{21}\\
& \forall n \operatorname{Prob}_{\tau_{B}}(\underset{\sim}{m}=n) \leqslant \beta \tag{22}
\end{align*}
$$

where $\beta$ is a parameter to be specified later.
We shall exhibit a strategy for $P I I$ which approaches $\bar{X}$. It is enough to consider the case where PI uses a pure strategy, hence a sequence of moves $\left\{i_{1}, \ldots, i_{n}, \ldots\right\}$. We shall still write $h_{n}$ for the $n$-stage history corresponding to these moves. (Note that here $h_{n}$ does not include the moves of PII.)

We now introduce

$$
\begin{aligned}
& p_{n}^{*}=\operatorname{Prob}_{\tau_{B}}\left(\underset{\sim}{m} \leqslant n \mid H_{n}\right) \\
& t_{n}^{*}=E_{\tau}\left({\underset{\sim}{m}}_{\underset{\sim}{m}} \mid \underset{\sim}{m} \leqslant n, H_{n}\right) \text { with } t_{k}=1_{\left\{i_{k}=\operatorname{Top}\right\}} .
\end{aligned}
$$

Hence $p_{n}^{*}$ is the "absorbing" probability up to stage $n$ and $t_{n}^{*}$ is the corresponding "absorbing" frequency.

The strategy $\tau$ is as follows.

- First PII uses $\tau(\bar{X})$ which is:
$-\quad$ play $\tau_{B}$ at stage $n+1$ if either
$\left(^{*}\right) \quad p_{n}^{*} \leqslant \beta$
or
$\left({ }^{* *}\right) \quad b_{1}\left(t_{n}^{*}\right) \geqslant-\frac{\beta L}{d}$ with $d=\max \left(\lambda, \frac{1}{\lambda}\right)$ where $-\lambda$ is the slope of the line $T^{*} B^{*}$.


## - $\quad$ if $\left({ }^{*}\right)$ and $\left({ }^{* *}\right)$ fail, play Left with probability $\beta$ if

$(* * *) p_{n}^{*} b_{1}\left(t_{n}^{*}\right)+\left(1-p_{n}^{*}\right) \bar{y}>0$.

- If at some stage $\theta_{1}+1,\left({ }^{*}\right),\left({ }^{* *}\right)$ and $\left({ }^{* * *}\right)$ fail, PII uses $\tau(\bar{Y})$ in the game starting at that stage, which is defined symmetrically (starting with $\tau_{A}$, with parameters $\eta_{A}$ and $\beta$ ).

Let us denote by $\theta_{1}, \theta_{1}+\theta_{2}, \ldots$, the "reversing times" defined by
on $\left\{1, \ldots, \theta_{1}\right\}$
PII plays $\tau(\bar{X})$
on $\left\{\theta_{1}+1, \ldots, \theta_{1}+\theta_{2}\right\}$
PII plays $\tau(\bar{Y})$
on $\left\{\theta_{1}+\theta_{2}+1, \ldots, \theta_{1}+\theta_{2}+\theta_{3}\right\} \quad$ PII plays $\tau(\bar{X})$, and so on,
and let $K_{1}, K_{2}, \ldots$, be the corresponding blocks of stages.

On each block $K_{i}$ we define the exceptional stages to be such that $\left({ }^{*}\right)$ and ( ${ }^{* *}$ ) fail and $\left({ }^{* * *}\right)$ holds. It follows then from the definitions, that there is at most a finite number $N(\alpha)$ or $N(\beta)$ of such stages.

Given $\epsilon>0$, we want to show that PII can approach $\bar{X}$ within $\epsilon$. We obviously can assume $\bar{x}>0$ (otherwise $P I I$ will approach $\bar{x}+\frac{\epsilon}{2}$ within $\frac{\epsilon}{2}$ ), and similarly $\bar{y}>0$.

Now this implies that for $\left({ }^{* * *}\right)$ and $\left({ }^{* *}\right)$ to fail the absorbing probability has to be greater than some $p_{B}>0$ (resp. $p_{A}$ ). It follows that after a finite number of "reversing times", the total absorbing probability $M(\epsilon)$ will be greater than $1-\frac{\epsilon}{3 L}$ hence the remaining payoff will be bounded by $\frac{\epsilon}{3}$.

Thus we denote by $M$ the finite number of blocks, and $\tau$ will approach $\bar{X}$ within $\frac{2 \epsilon}{3}$. Let

$$
\begin{aligned}
& \eta_{A}=\eta_{B}=\frac{\epsilon}{6}, \beta=\frac{\epsilon}{6 L d} p_{B}, \alpha=\frac{\epsilon}{6 L d} p_{A} \\
& N_{0}=\max (N(\alpha), N(\beta)), N_{1}=\max \left(N_{A}, N_{B}\right) \text { and } N=N_{0}+N_{1} .
\end{aligned}
$$

For each block of small length (i.e. less than $N$ ) we majorize the payoff per stage by $L$. For each other block $K_{i}$ we majorize the payoffs corresponding to the exceptional stage, and we denote by $\overline{\rho_{i}}$ the average vector payoff of the $\lambda_{i}$ other stages (i.e. where $P I I$ is using $\tau_{A}$ or $\tau_{B}$ ).

Then we obtain

$$
\begin{equation*}
n \bar{\gamma}_{n}(\sigma, \tau) \leqslant M N L+\sum_{i \in M} \lambda_{i} \overline{\rho_{i}} \tag{23}
\end{equation*}
$$

where $\bar{\gamma}_{n}$ is the vector payoff $\left(\bar{\gamma}_{n}^{A}, \bar{\gamma}_{n}^{B}\right)$ and $M N L$ is written for $M N L(1,1)$. Since $\Sigma \lambda_{i}+M N \geqslant n$ it is enough to prove

$$
\begin{equation*}
\overline{\rho_{i}} \leqslant \bar{X}+\frac{\epsilon}{3} \tag{24}
\end{equation*}
$$

and from (23) we obtain for large enough $n$

$$
\bar{\gamma}_{n}(\sigma, \tau) \leqslant \bar{X}+\frac{2 \epsilon}{3} .
$$

Now we write, with $p^{i}=p_{\theta_{i}}^{*}$ and $t^{i}=t_{\theta_{i}}^{*}$

$$
\begin{aligned}
\overline{\rho_{i}}= & p^{1}\binom{a_{1}\left(t^{1}\right)}{b_{1}\left(t^{1}\right)}+\ldots+\left(1-p^{1}\right)\left(1-p^{2}\right) \ldots\left(1-p^{i-2}\right) p^{i-1}\binom{a_{1}\left(t^{i-1}\right)}{b_{1}\left(t^{i-1}\right)} \\
& +\left(1-p^{1}\right) \ldots\left(1-p^{i-1}\right) \bar{g}_{i}
\end{aligned}
$$

where the first terms correspond to the absorbing payoffs obtained during the preceding blocks, and $\bar{g}_{i}$ is the new average payoff on block $K_{i}$ during the regular stages.

Assume $i$ odd. Then we shall first prove

$$
\begin{equation*}
\bar{g}_{i} \leqslant \bar{X}+\frac{\epsilon}{3} \tag{25}
\end{equation*}
$$

and then that (25) implies

$$
\begin{equation*}
p^{i-1}\binom{a_{1}\left(t^{i-1}\right)}{b_{1}\left(t^{i-1}\right)}+\left(1-p^{i-1}\right) \bar{g}_{i} \leqslant Y+\frac{\epsilon}{3} \tag{26}
\end{equation*}
$$

hence (24) by induction.
Let us now majorize $\bar{g}_{i}$.
Since $P I I$ is using $\tau_{B}$ and the number of stages is greater than $N_{B}$, the payoff in game $B$ is at most

$$
\bar{g}_{i}^{B} \leqslant \eta_{B}=\frac{\epsilon}{6} .
$$

As for the payoff in game $A$, we have at the last regular stage: either
(*) $p^{*} \leqslant \beta$, hence

$$
\begin{aligned}
\bar{g}_{i}^{A} & \leqslant \beta_{0} L+\left(1-\beta_{0}\right) \max \left(a_{12}, a_{22}\right) \text { for some } \beta_{0} \leqslant \beta \\
& \leqslant x+\beta L \quad \text { (using III) } \\
& \leqslant \bar{x}+\beta L \quad \text { by definition of } \bar{X} \\
& \leqslant \bar{x}+\frac{\epsilon}{6}
\end{aligned}
$$

or
$\left({ }^{* *}\right) b_{1}\left(t^{*}\right) \geqslant-\frac{\beta L}{d}$ and then :

$$
\bar{g}_{i}^{A} \leqslant p^{*}\left(x_{0}+\beta L\right)+\left(1-p^{*}\right) x
$$

where $\left(x_{0}, 0\right)$ is on $\left[T^{*}, B^{*}\right]$, hence by definition of $\bar{X}$

$$
\bar{g}_{i}^{A} \leqslant \bar{x}+\beta L \leqslant \bar{x}+\frac{\epsilon}{6}
$$

This proves (25).
As for (26), first note that $\left({ }^{* * *}\right)$ implies, by definition of $\theta_{i-1}$, that

$$
p^{i-1} a_{1}\left(t^{i-1}\right)+\left(1-p^{i-1}\right) \bar{x} \leqslant 0 .
$$

Hence it remains to majorize the second component. Denoting the stage $\theta_{i-1}-1$ by $k$, there are three cases:

- if $p_{k}^{*} \leqslant \alpha$, then $p^{i-1} \leqslant 2 \alpha$, thus $p^{i-1} b_{1}\left(t^{i-1}\right) \leqslant 2 \alpha L$
- if $a_{1}\left(t_{k}^{*}\right) \geqslant-\frac{\beta L}{d}$, then $b_{1}\left(t_{\dot{k}}^{*}\right) \leqslant y_{0}+\alpha L$
where $\left(0, y_{0}\right)$ is on the line $B^{*} X$. It follows that $p^{i-1} b_{1}\left(t^{i-1}\right) \leqslant y_{0}+2 \alpha L$.
- finally, if $p_{k}^{*} a_{1}\left(t_{k}^{*}\right)+\left(1-p_{k}^{*}\right) \bar{x}>0$, this implies $p_{k}^{*} b_{1}\left(t_{k}^{*}\right)<y_{0}$
hence $p^{i-1} b_{1}\left(t^{i-1}\right) \leqslant y_{0}+\alpha L$.
In both cases we obtain

$$
p^{i-1} b_{1}\left(t^{i-1}\right)+\left(1-p^{i-1}\right) \bar{g}_{i}^{B} \leqslant \bar{y}+2 \alpha L+\left(1-p_{A}\right) \frac{\epsilon}{3} \leqslant \bar{y}+\frac{\epsilon}{3}
$$

which gives (26) and achieves the proof that PII can approach $\bar{X}$ (or $\bar{Y}$ ).
It remains to show the following

## Lemma 10

Assume that PII can approach $U$ and $V$ with
(i) $U$ and $V \in H\left(B^{*}, T^{*}\right), u_{1}<v_{1}, u_{2}>v_{2}$.
(ii) $U \in H\left(B^{*}, V\right), V \in H\left(T^{*}, U\right)$.

Then PII can approach $W$ which is the intersection of $V B^{*}$ and $U T^{*}$.

## Proof

Since $D_{I I}$ is closed and convex, we can define $U\left(\lambda_{1}\right)$ and $v\left(\lambda_{2}\right)$ where

$$
\begin{aligned}
& U(\lambda)=\lambda T^{*}+(1-\lambda) U \\
& V(\lambda)=\lambda B^{*}+(1-\lambda) V
\end{aligned}
$$

and $\lambda_{1}=\max \left\{\lambda ; U(\lambda) \in D_{I I}\right\} ; \lambda_{2}=\max \left\{\lambda ; V(\lambda) \in D_{I I}\right\}$. If $W \notin D_{I I}$ we can redefine $U$ to be $U\left(\lambda_{1}\right)$ and $V$ to be $V\left(\lambda_{2}\right)$, and i), ii) still hold.

Introduce $\lambda_{0}$ such that $u_{1}\left(\lambda_{0}\right)=\nu_{1}\left(\lambda_{0}\right)$, and note that $\lambda_{0}>0$.
PII uses the following strategy $\tau$ : play Left with probability $\lambda_{0}$ at stage 1 ; from stage 2 on play according to $\tau_{U}$ (resp. $\tau_{V}$ ) if $i_{1}=$ Top (resp. Bottom), where $\tau_{U}$ (resp. $\tau_{V}$ ) approach $U$ (resp. $V$ ). The vector payoff that $\tau$ approaches is now:

$$
\begin{array}{ll}
\text { if } i_{1}=\text { Top, } & \lambda_{0} T^{*}+\left(1-\lambda_{0}\right) U=U\left(\lambda_{0}\right) \\
\text { if } i_{1}=\text { Bottom }, & \lambda_{0} B^{*}+\left(1-\lambda_{0}\right) V=V\left(\lambda_{0}\right) .
\end{array}
$$

But by the choice of $\lambda_{0}, U\left(\lambda_{0}\right)$ dominates $V\left(\lambda_{0}\right)$ or reciprocally, hence PII can approach either $U\left(\lambda_{0}\right)$ or $V\left(\lambda_{0}\right)$, contradicting the definition of $U$ or $V$.
Q.E.D.

It follows that PII can approach the extreme points of $\bar{D}$ and this finishes the proof of Proposition 9.
Q.E.D.

## Third case

Here we assume (I), (II) and (III') : $Z \notin H\left(T^{*}, B^{*}\right)$.
We first remark that PII can approach $Z$ by playing Right and (see Lemma 8) that $P I$ can force a payoff $\theta W^{*}+(1-\theta) Z$ with $W^{*} \in\left[B^{*}, T^{*}\right]$. It follows that if $Z=$ $=(0,0)$ then $D_{I}=D_{I I}=\left(\mathbf{R}_{+}\right)^{2}$ and obviously $\bar{v}=0$.

Hence we cạn assume $z_{1}>0$. Thus $z_{1}=a_{22}$ and we shall determine the points $(k, \varphi(k)), k \in\left[0, a_{22}\right]$ that PII can approach. (Obviously the analysis is similar if $z_{2}>0$, for the points $(\psi(k), k), k \in\left[0, b_{12}\right]$.) Given $k \in\left[a_{12}^{+}, a_{22}\right]$, let $t_{k} \in[0,1]$ be such that $a_{2}\left(t_{k}\right)=k$ and define $S_{k}=t_{k} T^{*}+\left(1-t_{k}\right) B^{*}$.

Let us now introduce $\varphi$ on $\left[a_{12}^{+}, a_{22}\right]$ such that, if $C_{k}=(k, \varphi(k))$, the line $S_{k} C_{k}$ is tangent to the graph $g(\varphi)$ of $\varphi$ at $C_{k}$ and $\varphi\left(a_{22}\right)=b_{12}^{+}$(i.e. $Z \in g(\varphi)$ ). Formally we obtain for the line $S_{k} C_{k}$

$$
x_{2}-\varphi(k)=\lambda(k)\left(x_{1}-k\right)
$$

Thus

$$
\lambda(k)=\varphi^{\prime}(k)
$$

which gives

$$
\varphi(k)=\frac{b_{11} a_{22}-b_{21} a_{12}}{a_{22}-a_{12}}+\frac{b_{11}-b_{21}}{a_{11}-a_{21}} k+K k^{\frac{a_{22}-a_{12}}{a_{11}+a_{22}-a_{12}-a_{21}}}
$$

with $K$ such that $\varphi\left(a_{22}\right)=b_{12}^{+}$.
Now if $a_{12}>0$, then $a_{11}=0$, ahd we define $g(\varphi)$ on $\left[0, a_{12}\right]$ to be the segment $T^{*}$ $C_{a_{12}}$.

We first prove the following

## Lemma 11

PII can approach $(k, \varphi(k)), \forall k \in\left[0, a_{22}\right]$.

## Proof

Let us assume $k \in\left[a_{12}^{+}, a_{22}\right]$.
The idea of the proof is the following: we shall define a finite sequence of vector payoffs on $g(\varphi), C(r), r=0, \ldots, R$, starting from $C(0)=C_{k}$ and reaching $C(R)=Z$.

The strategy for $P I I$ will be such that if the absorbing probability is small the non absorbing payoff approaches $C(0)$. If not, the absorbing payoff will be such that from some stage $n$, it will be enough for $P I I$ to approach $C(1)$, and so on. Since $P I I$ can approach $C(R)=Z$, the induction will be complete.

Given $R$ large in $N$ we introduce

$$
k_{r}=k+\frac{r}{R}\left(a_{22}-k\right), r=0, \ldots, R
$$

and we denote $t_{k_{r}}$ by $x_{r}, S_{k_{r}}$ by $S(r)$, and $C_{k_{r}}$ by $C(r)$.
Let $\tau_{r}$ be an $\alpha$-optimal strategy for $P I I$ in the game

$$
\left[\begin{array}{cc}
\left(1-x_{r}\right)^{*}-\left(1-x_{r}\right) \\
-x_{r}^{*} & x_{r}
\end{array}\right]
$$

with $\operatorname{Prob}_{\sigma, \tau_{r}}(\underset{\sim}{m}=n) \leqslant \alpha, \forall \sigma, \forall n$; and let $N_{r}$ be such that

$$
E_{\sigma, \tau_{r}}\left(\bar{q}_{n} \mid \underset{\sim}{m} \geqslant n\right) \leqslant \alpha, \forall n \geqslant N_{r}, \forall \sigma .
$$

We also define, as in the second case,

$$
p_{n}^{*}=\operatorname{Prob}(\underset{\sim}{m} \leqslant n) \text { and } t_{n}^{*}=E[\underset{\sim}{i} \underset{\sim}{i} \mid \underset{\sim}{m} \leqslant n] .
$$

Now $P I I$ starts by playing $\tau_{0}$ as long as
$\left(^{*}\right) \quad p_{n}^{*}\left[a_{1}\left(t_{n}^{*}-\frac{1}{R}\right)\right]-\alpha L+\left(1-p_{n}^{*}\right) c_{1}(1)>k$.
If (*) fails for the first time after stage $\theta_{1}, P I I$ uses $\tau_{1}$ in order to approach $C(1)$, in the game starting at stage $\theta_{1}+1$, conditionally on $\underset{\sim}{m}>\theta_{1}$. Hence he will play $\tau_{1}$ as long as

$$
p_{n}^{*}\left[a_{1}\left(t_{n}^{*}-\frac{1}{R}\right)\right]-\alpha L+\left(1-p_{n}^{*}\right) c_{1}(2)>k_{1}
$$



Thus it is enough to prove that $P I I$ approaches $C(0)$ within $\epsilon$ on the first block (i.e. from stage 1 to $\theta_{1}$ ), if $\theta_{1}$ is large enough, and that, if PII approaches $C$ (1) within $\epsilon$ on the second block conditionally on $\underset{\sim}{m}>\theta_{1}$, its total vector payoff on this block will be $C(0)$ within $\epsilon$.

Assume then that ( ${ }^{*}$ ) holds. Since PII is using $\tau_{0}$, its average payoff in game $A$ is at most $k+L \alpha$.

As for the absorbing payoff we have

$$
p_{n}^{*}\left(t_{n}^{*}-x_{0}\right) \leqslant \alpha
$$

hence

$$
p_{n}^{*} a_{1}\left(t_{n}^{*}-\frac{1}{R}\right)-\alpha L \leqslant p_{n}^{*} s_{1}(1)
$$

Since $C(0) \in H(S(1) C(1))\left({ }^{*}\right)$ implies

$$
p_{n}^{*} s_{2}(1)+\left(1-p_{n}^{*}\right) c_{2}(1) \leqslant \varphi(k)
$$

Now the non absorbing payoff in game $B$ is at most $z_{2} \leqslant c_{2}$ (1), thus

$$
\gamma_{n}^{B} \leqslant p_{n}^{*} b_{1}\left(t_{n}^{*}\right)+\left(1-p_{n}^{*}\right) c_{2}(1) \leqslant \varphi(k)+\alpha L D+\frac{L}{R} .
$$

Assume now that $P I I$ approaches $C$ (1) within $\epsilon$, in the second block, conditionally on $\underset{\sim}{m}>\theta_{1}$. Let $p=p_{\theta_{1}}^{*}$ and define $S$ to be the absorbing vector payoff corresponding to $\widetilde{t_{\theta_{1}}^{*}}=t$. Now if $M$ is on $\left[B^{*} T^{*}\right]$ with $p m_{1}=p a_{1}\left(t-\frac{1}{R}\right)-\alpha L$ then $\mid p m_{1}+$ $+(1-p) c_{1}-k \mid<\alpha L$. Now $p m_{1}<p s_{1}(1)$ implies as above $\mid p m_{2}+(1-p) c_{2}-$ $-\varphi(k) \mid<\alpha L d$. It follows that

$$
\begin{aligned}
& p s_{1}+(1-p)\left(c_{1}+\epsilon\right) \leqslant k+2 \alpha L+p \frac{L}{R}+(1-p) \epsilon \\
& p s_{2}+(1-p)\left(c_{2}+\epsilon\right) \leqslant \varphi(k)+2 \alpha L d+p \frac{L}{R}+(1-p) \epsilon
\end{aligned}
$$

Thus given $\epsilon$ we first choose $R>\frac{2 L}{\epsilon}$. This gives a minorant $q$ for the $p_{n}^{*}$ where $\left(^{*}\right)$ fails (for all $r$ ) and we take $\alpha<\frac{\epsilon q}{4 L d}$.

If $k \in\left[0, a_{12}\right]$ with $a_{12}>0$, then PII will play $\tilde{\alpha}$, where $\alpha$ is small, in order to reach an absorbing payoff $S^{*}$ on $\left[B^{*} T^{*}\right]$ satisfying

$$
\left|p_{n}^{*} s_{1}+\left(1-p_{n}^{*}\right) a_{12}-k\right|<\alpha L
$$

and then he will approach $C_{a_{12}}$ as above.
Q.E.D.

Let $\Delta=\left\{(x, y) \mid(x, y) \in M+\left(\mathbf{R}_{+}\right)^{2}\right.$ for some $\left.M \in g(\varphi) \cup g(\psi)\right\}$.
Thus it remains to prove

## Lemma 12

$D_{I}=\Delta$.

## Proof

We shall prove that $P I$ can force $H\left(S_{h} C_{h}\right), \forall C_{h} \in g(\varphi)$. (A similar proof works for $g(\psi)$ ) and we define $p, \alpha$ to be such that $D(p, \alpha)=H\left(S_{h} C_{h}\right)$.

Given $\tau, \epsilon$ and $R$ large in $N$, we define inductively, as in the first case

$$
\begin{aligned}
& \sigma_{0}=\text { Top } \\
& P^{*}(0)=\operatorname{Prob}_{\sigma_{0}, \tau}(\underset{\sim}{m}<+\infty)
\end{aligned}
$$

and $n_{0}$ and $P(0)$ with

$$
P(0)=\operatorname{Prob}_{\sigma_{0}, \tau}\left(\underset{\sim}{m} \leqslant n_{0}\right)>P^{*}(0)-\epsilon .
$$

Now given $\left(\sigma_{r-1}, n_{r-1}\right)$ we introduce

$$
\begin{aligned}
& \sigma_{r}=\text { play according to } \sigma_{r-1} \text { up to stage } n_{r-1}, \text { and then }\left(1-\frac{r}{R}, \frac{r}{R}\right) \\
& P^{*}(r)=\operatorname{Prob}_{\sigma_{r}, \tau}(\underset{\sim}{m}<+\infty)
\end{aligned}
$$

and finally $n_{r} \geqslant n_{r-1}$ and $P(r)$ such that

$$
\left.P(r)=\operatorname{Prob}_{\sigma_{r}}, \tau \underset{\sim}{m} \leqslant n_{r}\right)>P^{*}(r)-\epsilon .
$$

Introducing $\rho \in Q$ with

$$
\rho\left(\left[0, \frac{r}{R}\right]\right)=P(r)
$$

it follows, as in the first case, that PI can obtain for $n$ large enough

$$
\begin{equation*}
\varphi_{A}(\rho, x)=\int_{0}^{x} \hat{a}_{1}(t) d \rho(t)+(1-\rho(x)) \hat{a}_{2}(x), \text { where } \hat{a}_{i}(t)=a_{i}(t) \tag{27}
\end{equation*}
$$

in game $A$, up to $\epsilon$, by playing the relevant $\sigma_{r}$.

Note also that by playing $\sigma_{R}$ up to some large stage and then as in Lemma 8.2,PI can obtain, up to some $\epsilon$, a vector payoff

$$
\begin{equation*}
W=\rho(1) U+(1-\rho(1)) V \tag{28}
\end{equation*}
$$

where

$$
\rho(1) U=\left(\begin{array}{ll}
1 & \\
\int & \hat{a}_{1}(t) d \rho(t) \\
0 & \\
1 & \\
\int_{0} & \hat{b}_{1}(t) d \rho(t)
\end{array}\right)
$$

and

$$
V \in \Delta_{0}=\left\{\alpha Z+(1-\alpha) S ; \alpha \in(0,1], S \in\left[T^{*} B^{*}\right]\right\}
$$

Hence $P I$ can force the following

$$
\begin{aligned}
& \inf _{\rho \in Q}\left[p \max \left\{\sup _{0 \leqslant x \leqslant 1} \varphi_{A}(\rho, x), \rho(1) u_{1}+(1-\rho(1)) v_{1}\right\}\right. \\
& \quad+\hat{p}^{\prime} \max \left\{\sup _{0 \leqslant y \leqslant 1} \varphi_{B}(\rho, x), \rho(1) u_{2}+(1-\rho(1)) v_{2}\right\} .
\end{aligned}
$$

Note first that $W \in \Delta_{0}$. Hence if $w_{1} \geqslant z_{1}$, then $W \in D(p, \alpha)$. So it is enough to prove that for any $k \in\left[0, a_{22}\right]$

$$
\begin{equation*}
\varphi_{A}(\rho, x) \leqslant k \quad \forall x \in[0,1] \tag{29}
\end{equation*}
$$

and

$$
\begin{equation*}
\rho(1) u_{1}+\left(1-\rho_{1}\right) v_{1} \leqslant k \tag{30}
\end{equation*}
$$

which implies

$$
\begin{equation*}
\rho(1) u_{2}+\left(1-\rho_{1}\right) v_{2} \geqslant \varphi(k) \tag{31}
\end{equation*}
$$

i) Assume $k \in\left[a_{12}^{+}, a_{22}\right]$.

We shall introduce a distribution $\bar{\rho}$ (and a corresponding $\bar{W}$ ) satisfying $\bar{w}_{2}=\varphi(k)$, and we shall show first when $V=Z$, and then for $V \neq Z$, that $w_{2} \geqslant \bar{w}_{2}$, hence the result will follow.

So let

$$
\bar{\rho}(t)=1+K\left(t+\frac{a_{12}-a_{11}}{a_{11}+a_{22}-a_{12}-a_{21}}\right)^{\frac{a_{12}-a_{11}}{a_{11}+a_{22}-a_{12}-a_{21}}}
$$

where $K$ is such that $\bar{\rho}\left(\hat{t}_{k}\right)=0$. It is now easy to see that

$$
\begin{align*}
& \varphi_{A}(\bar{\rho}, x)=k \quad \forall x \in\left[\hat{t}_{k}, 1\right]  \tag{32}\\
& \varphi_{A}(\bar{\rho}, x) \leqslant k \quad \forall x \in[0,1] \\
& \rho(1) \bar{u}_{2}+(1-\rho(1)) z_{2}=\varphi(k) .
\end{align*}
$$

Let us prove that $\bar{\rho}$ is the best that $P I I$ can do.
Assume first that $V=Z$ :

- if $\rho(1) \geqslant \bar{\rho}(1)$, then $W$ belongs to $H(\bar{d})$ (by (III')), where $\bar{d}$ is the parallel to $B^{*} T^{*}$ through $\bar{W}$. Now (30) and (32) imply that $w_{2} \geqslant \bar{w}_{2}$.
- if $\rho(1) \leqslant \bar{\rho}(1),(29)$ and (32) imply then that $\rho(x) \geqslant \bar{\rho}(x)$ for $x$ in some neighbourhood of $\hat{t}_{k}$. (Note that the non absorbing payoff is greater than $k$ if $x>\hat{t}_{k}$.)

Let $x_{0}$ be the last point where

$$
\rho(x)=\bar{\rho}(x) \text { with } \rho \geqslant \bar{\rho} \text { on }[0, x] \text {. }
$$

By (29) and (32) we obtain

$$
\int_{0}^{x_{0}} \hat{a}_{1}(t)(d \rho(t)-d \bar{\rho}(t)) \leqslant 0
$$

Thus integrating by parts

$$
\left(a_{11}-a_{12}\right) \int_{0}^{x_{0}}(\rho(t)-\bar{\rho}(t) d t) \leqslant 0
$$

which is a contradiction if $\rho \neq \bar{\rho}$.
Next assume $V \neq Z$.
Using (29), we can assume $\nu_{1}>z_{1}$ (otherwise $\nu_{2} \geqslant z_{2}$ ). We add some mass to $\bar{\rho}$ at point 1 in order to get $\tilde{\rho}$ with

$$
\bar{\rho}(1) \bar{u}_{1}+(\widetilde{\rho}(1)-\bar{\rho}(1)) a_{21}+(1-\tilde{\rho}(1)) v_{1}=k
$$

By (32) it follows that the first component of $\tilde{\rho}(1) B^{*}+(1-\tilde{\rho}(1)) V$ is smaller than the first component of $\bar{\rho}(1) B^{*}+(1-\bar{\rho}(1)) Z$. Since $V \in \Delta_{0}$, we have the reverse the order on the second component, hence $(\bar{\rho}, Z)$ is better than $(\tilde{\rho}, V)$ for $P I I$.

We now compare $\widetilde{\rho}$ and $\rho$.

On the first component we have

$$
\tilde{\rho}(1) \tilde{u}_{1}+(1-\tilde{\rho}(1)) v_{1}=k \geqslant \rho(1) u_{1}+(1-\rho(1)) v_{1}
$$

and we shall prove that $\tilde{\rho}(1) \leqslant \rho(1)$, hence as above $w_{2} \geqslant \tilde{w}_{2}$. Otherwise we have

$$
\tilde{\rho}(1) \tilde{u}_{1}>\rho(1) u_{1}
$$

but

$$
\begin{aligned}
\tilde{\rho}(1) \tilde{u}_{1}= & \bar{\rho}(1) u_{1}+(\tilde{\rho}(1)-\bar{\rho}(1)) a_{21} \\
& \leqslant \bar{\rho}(1) \bar{u}_{1}+(\rho(1)-\bar{\rho}(1)) a_{21} \leqslant \rho(1) u_{1}
\end{aligned}
$$

since as above $\rho \geqslant \bar{\rho}$ and $\hat{a}_{1}$ (.) is decreasing.
This completes the proof for case i).
ii) Assume $a_{12}>0$ and $k \in\left[0, a_{12}\right]$.

Let $\lambda$ be such that $(1-\lambda) a_{12}=k$. Then $\rho_{k}$ is defined to be $\lambda \delta_{0}+(1-\lambda) \bar{\rho}_{a_{12}}$, $\delta_{0}$ being the Dirac mass at 0 and $\bar{\rho}_{a_{12}}$ corresponding to the $\bar{\rho}$ defined in i) for $k=a_{12}$.

It is straightforward to check that the analogue to (32) holds, and the proof is similar to i).
Q.E.D.

## Fourth case

It remains to study the games for which (I) holds and (II) fails. Note that

$$
a_{12}>0 \text { and } b_{22}>0 \text { imply } a_{11}=0 \text { and } b_{21}=0
$$

hence $P I I$ can approach $(0,0)$ by playing $\widetilde{\text { Left and }} \bar{v}=0$. Thus we can restrict ourselves to the following games.

$$
\begin{aligned}
& a_{11}=0>a_{21}, a_{12}>a_{22}^{+} \\
& b_{21}>b_{11}^{+}, b_{12} \geqslant b_{22}^{+} .
\end{aligned}
$$

The analysis is roughly the same as in the third case, the role of $Z$ now being played by a point $U$ on the $x$-axis.

Let $\bar{t}=\max \left\{t \mid b_{1}(t)>0\right\} \wedge 1$ (hence $\bar{t}=1$ if $\left.b_{11}>0\right)$ and let $U=\left(a_{2}(\bar{t}), 0\right)$.

## Lemma 13

PII can approach $U$ and cannot expect less.

## Proof

If PII desires a payoff 0 within $\epsilon^{2}$ in game $B$, then the absorbing probability when PI plays $\overparen{(\bar{t}-\epsilon)}$ has to be less than some $M \epsilon$. Hence the payoff in game $A$ will be at least $a_{2}(\bar{t})$ within $K \epsilon$ where $K$ depends on the $a_{i j}, b_{i j}$.

Now if PII uses an $\epsilon$-optimal strategy in game $B$ blocking at $\bar{t}$, his non absorbing payoff in game $A$ will be at most $a_{2}(\bar{t})+\epsilon L$ and his absorbing payoff is negative, hence the result follows.
Q.E.D.

Now for $k \in\left[a_{22}^{+}, a_{2}(\bar{t})\right]$ we define $t_{k}$ with $a_{2}\left(t_{k}\right)=k$ and $S_{k}$ to be the corresponding absorbing payoff. As in the third case $\varphi(k)$ is defined such that if $C_{k}=(k, \varphi(k))$ then $S_{k} C_{k}$ is tangent at $C_{k}$ to be graph of $\varphi$. It is then easy to see that we have the analogue of Lemmas 11 and 12.

Finally for $k \in\left[0, a_{22}^{+}\right]$it follows, like in case three that, denoting the point ( $a_{22}$, $\varphi\left(a_{22}\right)$ ) by $C$, if $a_{22}>0$, the graph of $\varphi$ is the line $B^{*} C$. This determines completely the Pareto boundary of $D$, hence $\bar{v}$.

It is straightforward to check that, due to the symmetry of the games, these four cases exhaust all the possibilities. Hence this complete the proof of Theorem 3.
Q.E.D.

## 5 Examples

1) $A=\left[\begin{array}{ll}1^{*} & 0 \\ 0^{*} & 0\end{array}\right] \quad B=\left[\begin{array}{ll}0^{*} & 0 \\ 0^{*} & 1\end{array}\right]$

This game was studied in Sorin [1980], and

$$
\underline{v}(p)=\lim v_{n}(p)=\operatorname{Cav} u(p)=u(p)=p(1-p)
$$

As for the minmax we have (see the first case)

$$
\begin{aligned}
& \quad \bar{v}(p)=\inf _{\rho \in Q} \sup _{t \in[0,1]}\left\{p \int_{0}^{1}(1-s) d \rho(s)+(1-p) t(1-\rho(t))\right\} \\
& =p(1-\exp (1-(1-p) / p)) . \\
& \text { 2) } A=\left[\begin{array}{cc}
1^{*} & 0 \\
0^{*} & 1
\end{array}\right] \quad B=\left[\begin{array}{cc}
0^{*} & 1 \\
1^{*} & 0
\end{array}\right]
\end{aligned}
$$

This is in the second case.

The extreme points of $D$ on its Pareto boundary are

$$
\begin{aligned}
& Y=(1 / 2,1) \quad \text { (play optimally in game } A) \\
& X=(1,1 / 2) \quad \text { (play optimally in game } B \text { ) } \\
& U=\left(\frac{2}{3}, \frac{2}{3}\right) \quad \text { intersection of } B^{*} X \text { and } T^{*} Y
\end{aligned}
$$

PII plays $\left(\frac{1}{3}, \frac{2}{3}\right)$ once and then approaches $X$ (resp. $Y$ ) if $i_{1}=B$ (resp. $T$ ). In this example, it can be shown, for $p=\frac{1}{2}$, that by using only a "mixture of Big Match strategies" as in the first case, PII cannot expect less than $\sqrt{3}-1$.
3) $A=\left[\begin{array}{ll}1^{*} & 0 \\ 0^{*} & 1\end{array}\right] \quad B=\left[\begin{array}{cc}0^{*} & \frac{3}{4} \\ 1^{*} & 0\end{array}\right]$ (second case)

$$
X=\left(1, \frac{3}{7}\right) \quad Y=\left(\frac{1}{2}, \frac{3}{4}\right) \quad U=\left(\frac{7}{13}, \frac{9}{13}\right)
$$

The strategy for $P I I$ to approach $U$ can be described by the following diagram


Abb.
4) $A=\left[\begin{array}{rr}8^{*} & -2 \\ -4^{*} & 1\end{array}\right] \quad B=\left[\begin{array}{rr}-3^{*} & 2 \\ 6^{*} & -4\end{array}\right]$ (case 3)

For $k \in[0,1], C_{k}=(k, \varphi(k))$ with $\varphi(k)=3-\frac{3}{4} k-\frac{1}{4} k^{1 / 5}$.
For $\lambda \in[0,2], C_{\lambda}=(\psi(\lambda), \lambda)$ with $\psi(\lambda)=4-\frac{4}{3} \lambda-\frac{1}{3} \quad \frac{\lambda}{2}{ }^{2 / 5}$.
5) $A=\left[\begin{array}{cc}0^{*} & 1 \\ -1^{*} & 0\end{array}\right] \quad B=\left[\begin{array}{cc}-1^{*} & 1 \\ 1^{*} & -1\end{array}\right] \quad$ (case 4)

For $k \in\left[0, \frac{1}{2}, C_{k}=(k, \varphi(k))\right.$ with $\varphi(k)=-1-2 k+2 e^{k-1 / 2}$.
6) $A=\left[\begin{array}{cc}0^{*} & 2 \\ -1^{*} & 1\end{array}\right] \quad B=\left[\begin{array}{cc}1^{*} & 0 \\ 2^{*} & 0\end{array}\right]$

For $k \in[0,2], C_{k}=(k, \varphi(k))$ with $\varphi(k)=(1-k)+e^{\frac{k}{2}-1}$ on $[1,2]$ and $\varphi$ is linear on $[0,1]$ with $C_{k}$ on $\left[B^{*}, C_{1}\right]$.

## 6 Concluding Remarks

1) We proved the existence of $\lim v_{n}, \underline{\nu}$ and $\bar{v}$ for the class of games under consideration. This results also hold for games with a lack of information, stochastic games, and the class studied in Sorin [1984].
2) However $\underline{v}$ and $\bar{v}$ may be different (see example 1), hence $G_{\infty}$ may have no value, which is neither the case for stochastic games nor for games with a lack of information on one side.
3) Moreover $\bar{v}$ may be a transcendental function (i.e. given a game with parameters in $\mathbf{Q}$ (or algebraic) $\bar{v}(p)$ may be a transcendental number) which is not the case for stochastic games or games with a lack of information.
4) Note that if the results are similar to those in Sorin [1984] the tools used seem to be necessarily rather different. See Example 2.
5) As a consequence of Remark 3, Part 3 we know that $\lim v_{n}$ and $\lim v_{\lambda}$ exist and are equal. This is the case for all zero-sum games where $\lim v_{n}$ is known to exist. An open
problem is to check whether this equality can be obtained directly.
6) As in Sorin [1984] we proved here that $\lim v_{n}$ is equal to the Maxmin. It is conjectured that this property holds for all stochastic games with lack of information on one side. (This would be, in particular, a consequence of the extension of MertensNeyman's Theorem [1981] to games with compact state spaces.)
7) In a forthcoming paper [Sorin, 1984] we show how the tools introduced here can be used to compute the minmax and the maxmin of a game with lack of information on both sides, and state dependent signalling matrices.

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[^0]:    ${ }^{1}$ Prof. Sylvain Sorin, Department de Mathématiques, Université Louis Pasteur, 7 rue Descartes, 67084 Strasbourg, France. This paper was written during a visit at Core. (CORE DR 8229).

